# Integrability and reversibility in systems of ODEs 

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Based on the works:

- Z. Hu, M. Han and V.R., Local Integrability of a Family of Three-Dimensional Quadratic Systems, Physica D, 265 (2013) 78-86.
- V. R. Y.-H. Xia and X. Zhang. Varieties of local integrability of analytic differential systems and their applications. J. Differential Equations, 257 (2014) 3079-3101.
- V. R. and D. S. Shafer, Time-reversibility of a 3-dim system, preprint, 2015.

Consider the system

$$
\begin{equation*}
\dot{u}=-v+p(u, v), \quad \dot{v}=u+q(u, v), \tag{1}
\end{equation*}
$$

where $p$ and $q$ are convergent series without free and linear terms. It has a center at the origin (all trajectories are ovals) iff it is locally analytically equivalent to a system of the form

$$
\begin{equation*}
\dot{x}=i x(1+g(x y)), \quad \dot{y}=-i y(1+g(x y)), \tag{2}
\end{equation*}
$$

where, $i=\sqrt{-1}, x=u+i v$ and $y=\bar{x}$.
$\Longrightarrow x y$ is a first integral of (2)
$\Longrightarrow u^{2}+v^{2}+$ h.o.t. is a first integral of (1)

## Theorem (Poincaré-Lyapunov)

System (1) has a center at the origin iff it admits a first integral of the form $u^{2}+v^{2}+$ h.o.t.

We discuss a generalization of the center problem (the Poincaré integrability problem) to $n$-dim systems.

$$
\begin{equation*}
\dot{x}=A x+\mathbf{f}(x) \tag{3}
\end{equation*}
$$

$A$ is $n \times n$ matrix, $x=\left(x_{1}, \ldots, x_{n}\right)^{\tau}, \mathbf{f}(x)=\left(f_{1}(x), \ldots, f_{n}(x)\right)^{\tau}$, and $f_{i}$ are series starting with at least quadratic terms.
Let $\lambda=\left(\lambda_{1}, \ldots, \lambda_{n}\right)$ be the $n$-tuple of eigenvalues of $A$. Set $\mathbb{Z}_{+}=\mathbb{N} \cup 0$. For $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right) \in \mathbb{Z}_{+}^{n}$ denote

$$
\langle\lambda, \alpha\rangle=\sum_{i=1}^{n} \alpha_{i} \lambda_{i}
$$

and $|\alpha|=\alpha_{1}+\cdots+\alpha_{n}$. Let

$$
\mathfrak{R}=\left\{\alpha \in \mathbb{Z}_{+}^{n}|\quad\langle\lambda, \alpha\rangle=0,|\alpha|>0\},\right.
$$

and denote by $r_{\lambda}$ the rank of vectors in the set $\mathfrak{R}$.

A substitution

$$
\begin{equation*}
x=\Phi(y):=y+\varphi(y), \tag{4}
\end{equation*}
$$

transforms (3) to its Poincaré-Dulac normal form, i.e. a system of the form

$$
\begin{equation*}
\dot{y}=A y+\mathbf{g}(y), \tag{5}
\end{equation*}
$$

where $\mathbf{g}(y)=\left(g_{1}(y), \ldots, g_{n}(y)\right)^{\tau}$ contains only resonant terms, that is, each monomial in $g_{k}, k=1, \ldots, n$, is of the form $g^{(\alpha)} y^{\alpha} e_{k}$ with

$$
\langle\lambda, \alpha\rangle-\lambda_{k}=0,
$$

where $e_{k}$ is the $n$-dimensional unit vector with its $n$th component equal to 1 and the others all equal to zero. We call the transformation (4) a normalization.
The normalization containing only nonresonant terms is unique. We call this normalization a distinguished normalization and term the corresponding Poincaré-Dulac normal form a distinguished normal form.

## Convergence of the normalizing transformation

Normalization (4) does not necessarily converge, so generally speaking $\varphi$ and $\mathbf{g}$ are formal power series.
Poincaré domain in $\mathbb{C}^{n}$ is the set of all points $\left(z_{1}, \ldots, z_{n}\right)$ such that the convex hull of the set $\left\{z_{1}, \ldots, z_{n}\right\} \subset \mathbb{C}$ does not contain the origin. Then if the vector $\left(\lambda_{1}, \ldots, \lambda_{n}\right)$ of eigenvalues of $A$ in (3) lies in the Poincaré domain then there exists a convergent normalizing transformation.

## Theorem (C. L. Siegel)

Suppose there exist positive constants $C>0$ and $\nu>0$ such that for all $\alpha \in \mathbb{N}_{0}^{n}$ such that $|\alpha|>1$ and for all $k \in\{1, \ldots, n\}$ the inequality

$$
\begin{equation*}
\left|\sum_{i=1}^{n} \alpha_{i} \lambda_{i}-\lambda_{k}\right| \geq C|\alpha|^{-\nu} \tag{6}
\end{equation*}
$$

holds. Then there exists a convergent transformation of (3) to normal form.

## Theorem ( V. A. Pliss)

Suppose that for system (3)
(i) the nonzero elements among the $\sum_{j=1}^{n} \alpha_{j} \lambda_{j}-\lambda_{k}$ satisfy condition (6)
(ii) some formal normal form of (3) is linear.

Then there exists a convergent transformation to normal form.
Bryuno conditions that together are sufficient for existence of a convergent normalizing transformation:

1) Condition $\omega$ : for $w_{\ell}=\min (\alpha, \lambda)$ over all $\alpha \in \mathbb{N}_{0}^{n}$ for which $(\alpha, \lambda) \neq 0$ and $|\alpha| \leq 2^{\prime}, \sum 2^{-\ell} \ln w_{\ell}<\infty$;
2) Condition $A$ (simplified version): some normal form has the form

$$
\begin{equation*}
\dot{\mathbf{y}}=(1+g(\mathbf{y})) A \mathbf{y}, \tag{7}
\end{equation*}
$$

that is, $\dot{y}_{j}=\lambda_{j} y_{j}(1+g(\mathbf{y}))$ for some scalar function $g(\mathbf{y})$.
Following to S. Walcher we say that (3) satisfies the Pliss-Bryuno condition if it can be transformed to (7) by a normalizing transformation.

For simplicity we assume that $A$ is in Jordan normal form and lower triangular.

## Definition

System (3) is (locally) analytically (or formally ) integrable if it has $n-1$ functionally independent analytic (or formal) first integrals in a neighborhood of the origin.

## Theorem (X. Zhang, Llibre-Pantazi-Walcher)

System (3) has $n-1$ functionally independent analytic first integrals in a neighborhood of the origin if and only if $r_{\lambda}=n-1$ and the distinguished normal form of (3) satisfies the Pliss-Bruno condition.

## Example: Recursive Construction of a Formal First Integral

$$
\begin{align*}
& \dot{u}=-v+P(u, v, w) \\
& \mathcal{X}: \quad \dot{v}=u+\widetilde{P}(u, v, w)  \tag{8}\\
& \dot{w}=-\lambda w+R(u, v, w)=\widetilde{Q}(u, v, w) \quad \lambda \in \mathbb{R} \backslash\{0\} \\
&
\end{align*}
$$

$P, Q$, and $R$ are real analytic in a neighborhood of the origin.
We look for a function $\Phi(u, v, w)$ with undetermined coefficients $\phi_{j k \ell}$,

$$
\begin{equation*}
\Phi(u, v, w)=u^{2}+v^{2}+\sum_{j+k+\ell=3} \phi_{j k \ell} u^{j} v^{k} w^{\ell}, \tag{9}
\end{equation*}
$$

such that

$$
\begin{equation*}
\frac{\partial \Phi}{\partial u} \widetilde{P}+\frac{\partial \Phi}{\partial v} \widetilde{Q}+\frac{\partial \Phi}{\partial w} \widetilde{R} \equiv 0 . \tag{10}
\end{equation*}
$$

Obstacles for the fulfillment of (10) will give us the necessary conditions for the existence of a first integral of the form

$$
\begin{equation*}
\Phi(u, v, w)=u^{2}+v^{2}+\ldots . \tag{11}
\end{equation*}
$$

A computational procedure to find the first $m-1$ conditions for integrability is as follows.

- Write down the initial string of (9) up to order $2 m$, $\Phi_{2 m}(u, v, w)=u^{2}+v^{2}+\sum_{j+k+\ell=3}^{2 m} \phi_{j k \ell} u^{j} v^{k} w^{\ell}$.
- For each $i=3, \ldots, 2 m+1$ equate coefficients of terms of order $i$ in the expression

$$
\begin{equation*}
\frac{\partial \Phi_{2 m}}{\partial u} \widetilde{P}+\frac{\partial \Phi_{2 m}}{\partial v} \widetilde{Q}+\frac{\partial \Phi_{2 m}}{\partial w} \widetilde{R}-g_{1}\left(u^{2}+v^{2}\right)^{2}-\cdots-g_{m-1}\left(u^{2}+v^{2}\right)^{m} \tag{12}
\end{equation*}
$$

to zero obtaining $2 m-2$ systems of linear variables in unknown variables $\phi_{j k \ell}$.

Computing in this way one obtains a list of polynomials, $g_{1}, g_{2}, g_{3}, \ldots$ in parameters of system (8). We call the polynomial $g_{i}$ the $i$-th focus quantity (Lyapunov number). Each polynomial $g_{i}$ represents an obstacle for existing of integral (9), that is, system (8) admits an integral (11) iff

$$
g_{1}=g_{2}=g_{3}=\cdots=0
$$

The set of systems with a first integral of the form (11) is the set of common zeros of an infinite system of polynomials

$$
\begin{equation*}
g_{1}=g_{2}=g_{3}=\cdots=0 \tag{13}
\end{equation*}
$$

Conditions (13) are the necessary conditions for existence of first integral $\Phi(u, v, w)=u^{2}+v^{2}+\ldots$ in system (8).

Two difficulties in computing the necessary conditions for integrability:

1) Polynomials $g_{1}, g_{2}, g_{3}, \ldots$ are not uniquely defined (depend on the choice of resonant terms).
Let $\mathcal{X}$ be the vector field associated to system (3).
Let $\psi(x)$ be a series. We call the term $\psi^{(\alpha)} x^{\alpha}$ a resonant term if $\alpha \in \mathfrak{R}$ ( $\langle\alpha, \lambda\rangle=0$ ).
2) Solving even a finite system of polynomials

$$
g_{1}=g_{2}=g_{3}=\cdots=g_{k}=0
$$

can be an extremely laborious problem.

## Uncertain choice of $g_{i}$

## Theorem (VR, Y. Xia, X. Zhang, J. Differential Equations, 2014)

For system (3) the following statements hold.
(a) There exist series $\psi(x)$ with its resonant monomials arbitrary such that

$$
\begin{equation*}
\mathcal{X}(\psi(x))=\sum_{\alpha \in \mathfrak{R}} p_{\alpha} x^{\alpha} \tag{14}
\end{equation*}
$$

where $p_{\alpha}$ are functions of the coefficients of (3).
(b) If the vector field (3) has $n-1$ functionally independent analytic or formal first integrals, then for any $\psi$ satisfying (14), we have

$$
\begin{equation*}
p_{\alpha}=0, \quad \text { for all } \quad \alpha \in \mathfrak{R} \tag{15}
\end{equation*}
$$

(c) Assume that the rank of $\mathfrak{R}$ is $k$, i.e. $r_{\lambda}=k$, and there are $k$ functionally independent $\psi^{(1)}, \ldots, \psi^{(k)}$, such that for the corresponding coefficients in (14) hold $\quad p_{\alpha}^{(i)}=0, \quad$ for all $\alpha \in \Re, i=1, \ldots, k$. Then the vector field $\mathcal{X}$ has exactly $k$ functionally independent analytic or formal first integrals.

## Definition

The variety of an ideal $I$ generated by $f_{1}\left(x_{1}, \ldots, x_{n}\right), \ldots, f_{1}\left(x_{1}, \ldots, x_{n}\right)$ of the polynomial ring $\mathbb{F}\left[x_{1}, \ldots, x_{n}\right]$ is the set of all points in $\mathbb{F}^{n}$ where all polynomials of $I$ vanish. (The variety of $I$ is denoted by $\mathbf{V}(I)$ ).
W.I.o.g we can take $\psi_{\alpha}^{(i)}=0$ for resonant $\alpha$. Then $p_{\alpha}$ are polynomials. Denote by $\mathcal{B}$ the ideal generated by the polynomials $p_{\alpha}$, for some choice of $n-1$ functionally independent functions $\psi^{(1)}, \ldots, \psi^{(n-1)}$ satisfying (14), i.e.

$$
\begin{equation*}
\mathcal{B}=\left\langle p_{\alpha}^{(i)} \mid \alpha \in \mathfrak{R}, \quad i=1, \ldots, n-1\right\rangle . \tag{16}
\end{equation*}
$$

By the equivalence of $(b)$ and (c) with $k=n-1$ the variety of $\mathcal{B}, \mathbf{V}(\mathcal{B})$, is the set of all points in the space of parameters of system (3), such that the corresponding systems have $n-1$ functionally independent integrals. We call $\mathbf{V}(\mathcal{B})$ the integrability variety of system (3).

To find the variety of $\mathcal{B}$ we can choose $n-1$ linearly independent vectors from $\mathfrak{R}$, let say $\alpha_{1}, \ldots, \alpha_{n-1} \in \mathfrak{R}$. Then $x^{\alpha_{1}}, \ldots, x^{\alpha_{k}}$ are functionally independent (integrals of the system of the linear approximation) and we look for $n-1$ functions $\psi_{s}(x)=x^{\alpha_{s}}+$ higher order terms satisfying

$$
\mathcal{X}\left(\psi^{(s)}(x)\right)=\sum_{\alpha \in \mathfrak{R}} p_{\alpha}^{(s)} x^{\alpha} .
$$

In actual calculations we can find only a finite number of polynomials $p_{\alpha}^{(s)}$, so we compute few first polynomials $p_{\alpha}^{(s)}$ which generate some ideal $\mathcal{B}_{m}$. Then,
a) we find the irreducible decomposition of $\mathbf{V}\left(\mathcal{B}_{m}\right)$ (solve the polynomial system $p_{\alpha}^{(s)}=0$ ),
b) using different methods we try to show that $\mathbf{V}(\mathcal{B})=\mathbf{V}\left(\mathcal{B}_{m}\right)$, that is, all systems corresponding to points from $\mathbf{V}\left(\mathcal{B}_{m}\right)$ have $n-1$ functionally independent analytic or formal first integrals.

## Solving polynomial systems

To make a progress it is crucial to have an efficient approach for solving systems of polynomials of many variables:

$$
\begin{align*}
& f_{1}\left(x_{1}, \ldots, x_{n}\right)=0 \\
& \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots  \tag{17}\\
& f_{m}\left(x_{1}, \ldots, x_{n}\right)=0
\end{align*}
$$

Let us find the variety in $\mathbb{C}^{3}$ of the ideal $I=\left\langle f_{1}, f_{2}, f_{3}, f_{4}\right\rangle$, where

$$
\begin{align*}
& f_{1}=8 x^{2} y^{2}+5 x y^{3}+3 x^{3} z+x^{2} y z \\
& f_{2}=x^{5}+2 y^{3} z^{2}+13 y^{2} z^{3}+5 y z^{4} \\
& f_{3}=8 x^{3}+12 y^{3}+x z^{2}+3  \tag{18}\\
& f_{4}=7 x^{2} y^{4}+18 x y^{3} z^{2}+y^{3} z^{3}
\end{align*}
$$

that is, the solution set of the system
$f_{1}=0, \quad f_{2}=0, \quad f_{3}=0, \quad f_{4}=0$. Under the lexicographic ordering with $x>y>z$ a Gröbner basis for $l$ is $G=\left\{g_{1}, g_{2}, g_{3}\right\}$, where $g_{1}=x$, $g_{2}=y^{3}+\frac{1}{4}, g_{3}=z^{2} . f_{1}=f_{2}=f_{3}=f_{4}=0 \Longleftrightarrow g_{1}=g_{2}=g_{3}=0$

This method ALWAYS works when the set of solution is finite: compute a Gröbner basis with respect to a lexicographic order, the basis MUST be triangular (like in Gauss row-echelon form, but with non-linear equations). We have the following computational obstacle:
in the example below the following polynomial appears in the intermediate computations of the Gröbner basis:

$$
\begin{equation*}
y^{3}-1735906504290451290764747182 \ldots \tag{19}
\end{equation*}
$$

The integer in the second term of the above polynomial contains roughly 80,000 digits.

- At least theoretically the Groebner basis theory allows to solve polynomial systems with a finite number of solutions.


## Infinite number of solutions

In generic case the variety consists of infinitely many points.
"To solve" a polynomial system means to find a decomposition of the variety of the ideal (the zero set) into irreducible components, that is, to find a representation $V=V_{1} \cup \cdots \cup V_{m}$, where each $V_{i}$ is irreducible.

Example. For $J=\langle x y, x z\rangle$, the variety of $J(x y=z x=0)$ is the union of the plane $x=0$ and the line $y=z=0$.

There are 3 algorithms for irreducible decompositions, all implemented in Singular:
G.-M. Greuel, G. Pfister, and H. Schönemann. Singular 3.0. A

Computer Algebra System for Polynomial Computations. Centre for Computer Algebra, University of Kaiserslautern (2005).
http://www.singular.uni-kl.de.

- Gianni-Trager-Zacharias (1988) (minAssGTZ)
- Shimoyama-Yokoyama (1996) (primdecSY)
- Characteristic sets method (Wang, 1992) (minAssChar) (the first one is implemented also in Maple)
>LIB "primdec.lib";
>ring $\mathrm{r}=0,(\mathrm{a} 20, \mathrm{a} 11, \mathrm{a} 02, \mathrm{a} 13, \mathrm{~b} 31, \mathrm{~b} 20, \mathrm{~b} 11, \mathrm{~b} 02), \mathrm{dp}$;
>poly g11=a11-b11;
>poly g22=a20*a02-b02*b20;
>poly g33=(3*a20^2*a13+8*a20*a13*b20+3*a02^2*b31
$\left.-8 * \mathrm{a} 02 * \mathrm{~b} 02 * \mathrm{~b} 31-3 * \mathrm{a} 13 * \mathrm{~b} 20^{\wedge} 2-3 * \mathrm{~b} 02 \wedge 2 * \mathrm{~b} 31\right) / 8$;
>poly g44=(-9*a20^2*a13*b11+a11*a13*b20^2 $\left.+9 * \mathrm{a} 11 * \mathrm{~b} 02^{\wedge} 2 * \mathrm{~b} 31-\mathrm{a} 02 \wedge 2 * \mathrm{~b} 11 * \mathrm{~b} 31\right) / 16$;
>poly g55=(-9*a20^2*a13*b02*b20+a20*a02*a13*b20^2
+9*a20*a02*b02^2*b31+18*a20*a13^2*b20*b31
$+6 * \mathrm{a} 02^{\wedge} 2 * \mathrm{a} 13 * \mathrm{~b} 31 \wedge 2-\mathrm{a} 02^{\wedge} 2 * \mathrm{~b} 02 * \mathrm{~b} 20 * \mathrm{~b} 31$
>ideal i = g11,g22,g33,g44,g55;
>minAssGTZ(i);
[1]:

$$
\begin{aligned}
& -[1]=a 02-3 * b 02 \\
& -[2]=a 11-b 11 \\
& -[3]=3 * a 20-b 20
\end{aligned}
$$

$$
\begin{aligned}
& -[1]=\mathrm{b} 11 \\
& -[2]=3 * \mathrm{a} 02+\mathrm{b} 02 \\
& -[3]=\mathrm{a} 11 \\
& -[4]=\mathrm{a} 20+3 * \mathrm{~b} 20 \\
& -[5]=3 * \mathrm{a} 13 * \mathrm{~b} 31+4 * \mathrm{~b} 20 * \mathrm{~b} 02
\end{aligned}
$$
\]

$$
\begin{aligned}
& -[1]=\mathrm{a} 11-\mathrm{b} 11 \\
& -[2]=\mathrm{a} 20 * \mathrm{a} 02-\mathrm{b} 20 * \mathrm{~b} 02 \\
& -[3]=\mathrm{a} 20 * \mathrm{a} 13 * \mathrm{~b} 20-\mathrm{a} 02 * \mathrm{~b} 31 * \mathrm{~b} 02 \\
& -[4]=\mathrm{a} 02^{\wedge} 2 * \mathrm{~b} 31-\mathrm{a} 13 * \mathrm{~b} 20^{\wedge} 2 \\
& -[5]=\mathrm{a} 20^{\wedge} 2 * \mathrm{a} 13-\mathrm{b} 31 * \mathrm{~b} 02^{\wedge} 2
\end{aligned}
$$
\]

## Modular arithmetic approach

The notorious computational difficulty of the Gröbner basis calculations over the field of rational numbers is an essential obstacle for using the Gröbner basis theory for the real world applications.

Modular calculations: choose a prime number $p$ and do all calculations modulo $p$, that is, in the finite field of the characteristic $p$ (the field $\mathbb{Z}_{p}=\mathbb{Z} / p$ ). The modular calculations still keep essential information on our original system and it is often possible to extract this information from the result of calculations in $\mathbb{Z}_{p}$ and to obtain the exact solution of polynomial system over the field of rational numbers.
P. Wang's algorithm for the rational reconstruction

Step 1. $u=\left(u_{1}, u_{2}, u_{3}\right):=(1,0, m), v=\left(v_{1}, v_{2}, v_{3}\right):=(1,0, c)$
Step 2. While $\sqrt{m / 2} \leq v_{3}$ do
$\left\{q:=\left\lfloor u_{3} / v_{3}\right\rfloor, r:=u-q v, u:=v, v:=r\right\}$
Step 3. If $\left|v_{2}\right| \geq \sqrt{m / 2}$ then error()
Step 4. Return $v_{3}, v_{2}$
$\lfloor\cdot\rfloor$ stands for the floor function.
Given an integer $c$ and a prime number $p$ the algorithm produces integers $v_{3}$ and $v_{2}$ such that $v_{3} / v_{2} \equiv c(\bmod p)$, that is, $v_{3}=v_{2} c+p t$ with some $t$. If such a number $v_{3} / v_{2}$ does need not exist the algorithm returns "error()".
P. Wang's algorithm for the rational reconstruction

Step 1. $u=\left(u_{1}, u_{2}, u_{3}\right):=(1,0, m), v=\left(v_{1}, v_{2}, v_{3}\right):=(1,0, c)$
Step 2. While $\sqrt{m / 2} \leq v_{3}$ do
$\left\{q:=\left\lfloor u_{3} / v_{3}\right\rfloor, r:=u-q v, u:=v, v:=r\right\}$
Step 3. If $\left|v_{2}\right| \geq \sqrt{m / 2}$ then error()
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$\lfloor\cdot\rfloor$ stands for the floor function.
Given an integer $c$ and a prime number $p$ the algorithm produces integers $v_{3}$ and $v_{2}$ such that $v_{3} / v_{2} \equiv c(\bmod p)$, that is, $v_{3}=v_{2} c+p t$ with some
$t$. If such a number $v_{3} / v_{2}$ does need not exist the algorithm returns "error()".
For the discussed example computing the Gröbner basis of (18) over the field of characteristic 32003 we find $G=\left\{x, y^{3}+8001, z^{2}\right\}$. Rational reconstruction yields $8001 \equiv 1 / 4(\bmod 32003)$. Therefore the reconstructed (lifted) Gröbner basis is $G=\left\{x, y^{3}+1 / 4, z^{2}\right\}$.

## Radical Membership Test

For a polynomial $f$ and an ideal $I=\left\langle f_{1}, \ldots, f_{m}\right\rangle$ in $k\left[x_{1}, \ldots, x_{n}\right], k=\mathbb{C}$, $f$ is equal to zero on $\mathbf{V}(I)$ ) if and only if the reduced Gröbner basis of the ideal $\left\langle 1-w f, f_{1}, \ldots, f_{m}\right\rangle$ (here $w$ is a new variable) is equal to $\{1\}$.

Allows to check if zero sets of $I=\left\langle f_{1}, \ldots, f_{m}\right\rangle$ and $J=\left\langle h_{1}, \ldots, h_{s}\right\rangle$ are the same in $\mathbb{C}^{n}$.

## Decomposition Algorithm with Modular Arithmetics

## (VR and M. Prešern, J. Comput. Appl. Math., 2011)

- Choose a prime number $p$ and compute the minimal associated primes $\tilde{Q}_{1}, \ldots, \tilde{Q}_{s}$ of $I=\left\langle f_{1}, \ldots, f_{s}\right\rangle$ in $\mathbb{Z}_{p}\left[x_{1}, \ldots, x_{n}\right]$.
- Using the rational reconstruction algorithm lift the ideals $\tilde{Q}_{i}$ $(i=1, \ldots, s)$ to the ideals $Q_{i}$ in $\mathbb{Q}\left[x_{1}, \ldots, x_{n}\right]$
- For each $i$ using the radical membership test check whether the original polynomials $f_{1}, \ldots, f_{s}$ vanish on the components $Q_{i}$ of the decomposition (on $\mathbf{V}\left(Q_{i}\right)$ ), i.e. whether the reduced Gröbner basis of the ideal $\left\langle 1-w f, Q_{i}\right\rangle$ is equal to $\{1\}$. If "yes", then go to the step 4, otherwise take another prime $p$ and go to step 1 .
- Compute $Q=\cap_{i=1}^{s} Q_{i} \subset \mathbb{Q}\left[x_{1}, \ldots, x_{n}\right]$.
- Check that $\sqrt{Q}=\sqrt{I}$, i.e, $\forall g \in Q$ the reduced $G B$ of the ideal $\langle 1-w g, I\rangle$ is $\{1\}$ and $\forall f \in I$ the reduced GB of $\langle 1-w f, Q\rangle$ is equal to $\{1\}$. If it is the case then $\mathbf{V}(I)=\cup_{i=1}^{s} \mathbf{V}\left(Q_{i}\right)$. If not, then choose another prime $p$ and go to Step 1.


## Example: a 3-dim system

System with $(0:-1: 1)$ resonant point at the origin:

$$
\begin{align*}
& \dot{x}_{1}=\sum_{i+j+k=2}^{m} p_{i j k} x_{1}^{i} x_{2}^{j} x_{3}^{k}=P(x), \\
& \dot{x}_{2}=-x_{2}+\sum_{i+j+k=2}^{m} q_{i j k} x_{1}^{i} x_{2}^{j} x_{3}^{k}=Q(x),  \tag{20}\\
& \dot{x}_{3}=x_{3}+\sum_{i+j+k=2}^{m} r_{i j k} x_{1}^{i} x_{2}^{j} x_{3}^{k}=R(x),
\end{align*}
$$

$P, Q, R$ are polynomials and $x=\left(x_{1}, x_{2}, x_{3}\right) \in \mathbb{C}^{3}$.
For system (20) $\lambda=(0,-1,1)$, thus, the set $\mathfrak{R}_{\lambda}$ is

$$
\begin{equation*}
\mathfrak{R}=\left\{\alpha \in \mathbb{N}_{+}^{3} \mid \alpha_{2}=\alpha_{3}\right\} . \tag{21}
\end{equation*}
$$

$$
\begin{equation*}
\psi_{1}=x_{1}+\sum_{|\alpha|>1} \phi^{(\alpha)} x^{\alpha} \tag{22}
\end{equation*}
$$

$$
\begin{equation*}
\psi_{2}=x_{2} x_{3}+\sum_{|\alpha|>2} \psi^{(\alpha)} x^{\alpha} . \tag{23}
\end{equation*}
$$

There are series $\psi_{1}(x)$ and $\psi_{2}(x)$,

$$
\begin{gather*}
\psi_{1}=x_{1}+\sum_{|\alpha|>1} \psi_{1}^{(\alpha)} x^{\alpha}  \tag{24}\\
\psi_{2}=x_{2} x_{3}+\sum_{|\alpha|>2} \psi_{2}^{(\alpha)} x^{\alpha} \tag{25}
\end{gather*}
$$

such that

$$
\begin{equation*}
\frac{\partial \psi_{1}}{\partial x_{1}} P+\frac{\partial \psi_{1}}{\partial x_{2}} Q+\frac{\partial \psi_{1}}{\partial x_{3}} R=\sum_{\alpha \in \mathfrak{R}} g_{\alpha}(a, b, c) x^{\alpha} \tag{26}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{\partial \psi_{2}}{\partial x_{1}} P+\frac{\partial \psi_{2}}{\partial x_{2}} Q+\frac{\partial \psi_{2}}{\partial x_{3}} R=\sum_{\alpha \in \mathfrak{R}} h_{\alpha}(a, b, c) x^{\alpha} \tag{27}
\end{equation*}
$$

where $P, Q, R$ are the right hand sides of (20) and $g_{\alpha}, h_{\alpha}(\alpha \in \mathfrak{R})$ are polynomials in ( $a, b, c$ ).

Denote by $\mathcal{B}$ the ideal generated by the polynomials $g_{\alpha}$ and $h_{\alpha}$, $\mathcal{B}=\left\langle g_{\alpha}, h_{\alpha} \mid \alpha \in \mathfrak{R}\right\rangle$, and by $\mathbf{V}(\mathcal{B})$ its variety $-\mathbf{V}(\mathcal{B})$ is the integrability variety of (20).

The set of all integrable systems (20) in the space of parameters of the system is the variety $\mathbf{V}(\mathcal{B})$ of the Bautin ideal $\mathcal{B}$ and it is the same for any choice of series (24) and polynomials $g_{\alpha}, h_{\alpha}(\alpha \in \mathfrak{R})$ satisfying (26) and (27).

After decomposition of $\mathbf{V}(\mathcal{B})$ using the decomposition algorithm with modular arithmetic we obtain the necessary condition of integrability. The next step: prove their sufficiency.

Two main mechanisms for integrability:

- Darboux integrability
- Time-reversibility

$$
\begin{equation*}
\frac{d \mathbf{z}}{d t}=F(\mathbf{z}) \quad(\mathbf{z} \in \Omega), \tag{28}
\end{equation*}
$$

$F: \Omega \mapsto T \Omega$ is a vector field and $\Omega$ is a manifold.

## Definition

A time-reversible symmetry of (28) is an invertible map $T: \Omega \mapsto \Omega$, such that

$$
\begin{equation*}
\frac{d(T \mathbf{z})}{d t}=-F(T \mathbf{z}) . \tag{29}
\end{equation*}
$$

By Llibre, Pantazi and Walcher (2012) if a system (30) is time-reversible with respect to a linear invertible transformation which permutes $x_{2}$ and $x_{3}$ then it is integrable.
$\dot{x}_{1}=\sum a_{j k \mid} x_{1}^{j} x_{2}^{k} x_{3}^{\prime}, \quad \dot{x}_{2}=x_{2} \sum b_{m n p} x_{1}^{m} x_{2}^{n} x_{3}^{p}, \quad \dot{x}_{3}=x_{3} \sum c_{q r s} x_{1}^{q} x_{2}^{r} x_{3}^{s}$.
Let $u, v, w$ be the number of parameters of the first, the second and the third equation, respectively. By $(a, b, c)$ we denote the $(u+v+w)$-tuple of parameters of system (30).
System (30) is time-reversible if there exists an invertible matrix $T$ such that

$$
\begin{equation*}
T^{-1} \circ f \circ T=-f \tag{31}
\end{equation*}
$$

We look for a transformation $T$ in the form

$$
T=\left(\begin{array}{lll}
1 & 0 & 0  \tag{32}\\
0 & 0 & \gamma \\
0 & 1 / \gamma & 0
\end{array}\right)
$$

(31) is satisfied for $T$ defined by (32) if and only if

$$
\begin{equation*}
a_{j k l}=-\gamma^{I-k} a_{j l k}, \quad b_{m n p}=-\gamma^{p-n} c_{m p n} . \tag{33}
\end{equation*}
$$

Denote by $k[a, b, c]$ the ring of polynomials in parameters of system (30) with the coefficients in a field $k$ and

$$
\begin{equation*}
H=\left\langle 1-y \gamma, a_{j k l}+\gamma^{l-k} a_{j l k}, b_{m n p}+\gamma^{p-n} c_{m p n}\right\rangle, \tag{34}
\end{equation*}
$$

where $y$ is a new variable.

## Rational implicitization

Suppose we are given the system of equations

$$
\begin{equation*}
x_{1}=\frac{f_{1}\left(t_{1}, \ldots, t_{m}\right)}{g_{1}\left(t_{1}, \ldots, t_{m}\right)}, \ldots, x_{n}=\frac{f_{n}\left(t_{1}, \ldots, t_{m}\right)}{g_{n}\left(t_{1}, \ldots, t_{m}\right)}, \tag{35}
\end{equation*}
$$

where $f_{j}, g_{j} \in k\left[t_{1}, \ldots, t_{m}\right]$ for $j=1, \ldots, n$. Let $W=\mathbf{V}\left(g_{1} \cdots g_{n}\right)$.
Equations (35) define

$$
F: k^{m} \backslash W \rightarrow k^{n}
$$

by

$$
\begin{equation*}
F\left(t_{1}, \ldots, t_{m}\right)=\left(\frac{f_{1}\left(t_{1}, \ldots, t_{m}\right)}{g_{1}\left(t_{1}, \ldots, t_{m}\right)}, \ldots, \frac{f_{n}\left(t_{1}, \ldots, t_{m}\right)}{g_{n}\left(t_{1}, \ldots, t_{m}\right)}\right) \tag{36}
\end{equation*}
$$

The image of $k^{m} \backslash W$ under $F$ denote by $F\left(k^{m} \backslash W\right)$ is not necessarily an affine variety.

Consequently we look for the smallest affine variety that contains $F\left(k^{m} \backslash W\right)$, i.e, its Zariski closure $\overline{F\left(k^{m} \backslash W\right)}$. The problem of finding $\overline{F\left(k^{m} \backslash W\right)}$ is known as the problem of rational implicitization (e.g. Cox et al, 2003).

## Rational implicitization theorem

Let $k$ be an infinite field, let $f_{1}, \ldots, f_{n}$ and $g_{1}, \ldots, g_{n}$ be elements of $k\left[t_{1}, \ldots, t_{m}\right]$, let $W=\mathbf{V}\left(g_{1} \cdots g_{n}\right)$, and let $F: k^{m} \backslash W \rightarrow k^{n}$, be the function defined by equations (36). Set $g=g_{1} \cdots g_{n}$. Consider the ideal

$$
J=\left\langle f_{1}-g_{1} x_{1}, \ldots, f_{n}-g_{n} x_{n}, 1-g y\right\rangle \subset k\left[y, t_{1}, \ldots, t_{m}, x_{1}, \ldots, x_{n}\right],
$$

and let

$$
\begin{equation*}
J_{m+1}=J \cap k\left[x_{1}, \ldots, x_{n}\right] . \tag{37}
\end{equation*}
$$

Then $\mathbf{V}\left(J_{m+1}\right)$ is the smallest variety in $k^{n}$ containing $F\left(k^{m} \backslash W\right)$.
$J_{m+1}$ is computing using the Elimination Theorem.

## Elimination Theorem

Fix the lexicographic term order on the ring $k\left[x_{1}, \ldots, x_{n}\right]$ with $x_{1}>x_{2}>\cdots>x_{n}$ and let $G$ be a Groebner basis for an ideal I of $k\left[x_{1}, \ldots, x_{n}\right]$ with respect to this order. Then for every $\ell, 0 \leq \ell \leq n-1$, the set $G_{\ell}:=G \cap k\left[x_{\ell+1}, \ldots, x_{n}\right]$ is a Groebner basis for the ideal $I_{\ell}=I \cap k\left[x_{\ell+1}, \ldots, x_{n}\right]$ (the $\ell$-th elimination ideal of $I$ ).

## Computation of $\mathcal{I}=k[a, b] \cap H$

## Theorem (Hu, Han, R., 2013)

The Zariski closure of all time-reversible (with respect to (32)) systems inside the family (30) with coefficients in the field $k(k$ is $\mathbb{R}$ or $\mathbb{C})$ is the variety $\mathbf{V}\left(I_{S}\right)$ of the ideal

$$
\begin{equation*}
I_{S}=k[a, b, c] \cap H . \tag{38}
\end{equation*}
$$

A generating set for $I_{S}$ (called the Sibirsky ideal) is obtained by computing a Groebner basis for $H$ with respect to any elimination order with $\{y, \gamma\}>\{a, b, c\}$ and choosing from the output list the polynomials which do not depend on $y$ and $\gamma$.

## Corollary

Let $I_{S}$ be ideal (38) of system (20). Then all systems from $\mathbf{V}\left(I_{S}\right)$ are integrable.

# A generalization in the case of Lotka-Volterra system, V.R. \& D. Shafer, preprint, 2015 

$$
\begin{equation*}
\dot{x}_{1}=x_{1} A_{1}\left(x_{1}, x_{2}, x_{3}\right), \dot{x}_{2}=x_{2}\left(1+A_{2}\left(x_{1}, x_{2}, x_{3}\right)\right), \dot{x}_{3}=-x_{3}\left(1+A_{3}\left(x_{1}, x_{2}, x_{3}\right)\right) \tag{39}
\end{equation*}
$$

## Theorem

Suppose $A_{j}(x, y, z)$ is a homogeneous polynomial function of degree $m$, $j \in\{1,2,3\}$ and that system (39) is transformed to system
$\dot{y}_{1}=y_{1} B_{1}\left(y_{1}, y_{2}, y_{3}\right), \dot{y}_{2}=-y_{2}\left(1+h\left(y_{1}, y_{2}, y_{3}\right)\right), \dot{y}_{3}=y_{3}\left(1-h\left(y_{1}, y_{2}, y_{3}\right)\right)$.
by

$$
\begin{equation*}
y_{1}=\frac{k_{1} x_{1}}{f^{1 / m}}, y_{2}=\frac{k_{2} x_{3}}{f^{1 / m}}, y_{3}=\frac{k_{3} x_{2}}{f^{1 / m}}, \tag{40}
\end{equation*}
$$

where $f=1+F$ and $F(x, y, z)$ is homogeneous polynomial function of degree $m$.
If $B\left(y_{1}, y_{3}, y_{2}\right)=-B\left(y_{1}, y_{2}, y_{3}\right)$ and $h\left(y_{1}, y_{3}, y_{2}\right)=-h\left(y_{1}, y_{2}, y_{3}\right)$ then system (39) has two functionally independent local analytic first integrals in a neighborhood of the origin.

Moreover:

$$
\begin{aligned}
& F=\frac{1}{2}\left(A_{2}+A_{3}\right) \quad f=1+F \\
& G(x, y, z)=F\left(\frac{x}{k_{1}}, \frac{z}{k_{3}}, \frac{y}{k_{2}}\right) \quad g=1-G .
\end{aligned}
$$

$$
\begin{gather*}
u_{j}(\mathbf{x}) \stackrel{\text { def }}{=} x_{j} \frac{\partial f}{\partial x_{j}}(\mathbf{x}), \quad j \in\{1,2,3\} \\
u_{j}(\mathbf{x})=g(\mathbf{y})^{-1} u_{j}\left(\frac{y_{1}}{k_{1}}, \frac{y_{3}}{k_{3}}, \frac{y_{2}}{k_{2}}\right) \stackrel{\text { def }}{=} g(\mathbf{y})^{-1} \widehat{u}_{j}(\mathbf{y}) . \\
A_{j}(\mathbf{x})=g(\mathbf{y})^{-1} A_{j}\left(\frac{\left(\frac{1}{1}\right.}{k_{1}}, \frac{y_{3}}{k_{3}}, \frac{y_{2}}{k_{2}}\right) \stackrel{\text { def }}{=} g(\mathbf{y})^{-1} \widehat{A}_{j}(\mathbf{y}), \\
{\left[\widehat{u}_{1} \widehat{A}_{1}+\widehat{u}_{2}\left(g+\widehat{A}_{2}\right)-\widehat{u}_{3}\left(g+\widehat{A}_{3}\right)\right] \stackrel{\text { def }}{=} S .} \\
B=\widehat{A}_{1}-\frac{1}{m} S \quad \text { and } \quad h=-\frac{1}{2}\left(\widehat{A}_{2}-\widehat{A}_{3}\right)+\frac{1}{m} S . \tag{42}
\end{gather*}
$$

## Example

Some conditions for complete integrability of system

$$
\begin{align*}
& \dot{x}_{1}=x_{1}\left(a_{1} x_{1}^{2}+a_{2} x_{1} x_{2}+a_{4} x_{2}^{2}+a_{3} x_{1} x_{3}+a_{5} x_{2} x_{3}+a_{6} x_{3}^{2}\right) \\
& \dot{x}_{2}=x_{2}\left(1+b_{1} x_{1}^{2}+b_{2} x_{1} x_{2}+b_{4} x_{2}^{2}+b_{3} x_{1} x_{3}+b_{5} x_{2} x_{3}+b_{6} x_{3}^{2}\right)  \tag{43}\\
& \dot{x}_{3}=-x_{3}\left(1+c_{1} x_{1}^{2}+c_{2} x_{1} x_{2}+c_{4} x_{2}^{2}+c_{3} x_{1} x_{3}+c_{5} x_{2} x_{3}+c_{6} x_{3}^{2}\right)
\end{align*}
$$

## Theorem

System (43) admits two analytic local first integrals of the form $\Psi_{1}\left(x_{1}, x_{2}, x_{3}\right)=x_{1}+\cdots$ and $\Psi_{2}\left(x_{1}, x_{2}, x_{3}\right)=x_{2} x_{3}+\cdots$ provided the parameter string $(a, b, c)$ lies in the set $\mathbf{V}\left(I_{1}\right) \cup \mathbf{V}\left(I_{2}\right) \cup \mathbf{V}\left(I_{3}\right) \cup \mathbf{V}\left(I_{4}\right)$ for the ideals:

| Ideal | Generators |
| :---: | :---: |
| $I_{1}$ | $a_{1}, a_{5}, b_{1}, b_{2}, b_{3}, b_{5}, b_{6}, c_{1}, c_{2}, c_{3}, c_{4}, c_{5}, a_{3}^{2} b_{4}+a_{2}^{2} c_{6}, a_{3}^{2} a_{4}+a_{2}^{2} a_{6}+$ |
| $\mathrm{I}_{2}$ | $\begin{aligned} & a_{1}, a_{5}, b_{1}, b_{5}, b_{6}, c_{1}, c_{4}, c_{5}, a_{3}+b_{3}, a_{2}-c_{2}, a_{6} b_{4}-a_{4} c_{6}+b_{4} c_{6}, a_{6} b_{3} \\ & a_{4} b_{2}+a_{4} c_{2}-2 b_{4} c_{2}, a_{4} b_{3}+b_{3} b_{4}+a_{4} c_{3}-b_{4} c_{3}, a_{6} b_{2}+a_{6} c_{2}+b_{2} c_{6} \\ & b_{2} b_{3} 3 b_{3} c_{2} b_{2} c_{3}+c_{2} c_{3}, 2 a_{6} c_{2}^{2}+2 a_{4} c_{3}^{2}+b_{2} c_{2} c_{6}+7 c_{2}^{2} c_{6}, 4 b_{3}^{2} b_{4} \\ & 4 b_{3} b_{4} c_{3}+b_{2}^{2} c_{6}+2 b_{2} c_{2} c_{6}-3 c_{2}^{2} c_{6}, 4 b_{4} c_{3}^{2}+b_{2}^{2} c_{6}+6 b_{2} c_{2} c_{6}+9 c_{2}^{2} c_{6} \end{aligned}$ |
| $I_{3}$ | $a_{1}, a_{5}, b_{1}-c_{1}, b_{5}-c_{5}, a_{2} b_{3}+a_{3} c_{2}, a_{3} b_{2}+a_{2} c_{3}, a_{4} b_{6}+a_{6} c_{4}, a_{6} b_{4}+$ $b_{4} b_{6}-c_{4} c_{6}, a_{2}^{2} b_{6}-a_{3}^{2} c_{4}, a_{3}^{2} a_{4}+a_{2}^{2} a_{6}, a_{6} b_{2}^{2}+a_{4} c_{3}^{2}, a_{3}^{2} b_{4}-a_{2}^{2} c_{6}, b_{3}^{2} b_{4}$ $b_{6} c_{2}^{2}-b_{3}^{2} c_{4} a_{4} b_{3}^{2}+a_{6} c_{2}^{2}, b_{2}^{2} b_{6}-c_{3}^{2} c_{4}, b_{4} c_{3}^{2}-b_{2}^{2} c_{6}, a_{2} b_{2} b_{6}+a_{3} c_{3} c_{4}$, $a_{2} b_{6} c_{2}+a_{3} b_{3} c_{4}, a_{2} a_{6} b_{2}-a_{3} a_{4} c_{3}, a_{3} a_{4} b_{3}-a_{2} a_{6} c_{2}, a_{3} b_{3} b_{4}+a_{2} c_{2} c_{6}, a_{3}$ $a_{6} b_{2} c_{2}+a_{4} b_{3} c_{3}, b_{2} b_{6} c_{2}-b_{3} c_{3} c_{4}, b_{3} b_{4} c_{3}-b_{2} c_{2} c_{6}$ |
| $I_{4}$ | $a_{1}, a_{5}, b_{1}, c_{1}, a_{3}+b_{3}, a_{2}-c_{2}, a_{4}+b_{4}, a_{6}-c_{6}, b_{5}-c_{5}, b_{4} b_{6}-c_{4} c_{6}$, $2 b_{2} b_{6}-3 b_{3} c_{5}-c_{3} c_{5}+2 b_{2} c_{6}, b_{6} c_{4}-c_{5}^{2}+b_{4} c_{6}+2 c_{4} c_{6}, 2 b_{4} c_{3}+2 c_{3} c^{2}$ $2 b_{6} c_{2}+b_{3} c_{5}-c_{3} c_{5}+2 c_{2} c_{6}, b_{2} b_{3}+3 b_{3} c_{2}-b_{2} c_{3}+c_{2} c_{3}, 2 b_{3} b_{4}+2 b_{3}$ $b_{4} c_{5}^{2}-b_{4}^{2} c_{6}-2 b_{4} c_{4} c_{6}-c_{4}^{2} c_{6}, 2 c_{3} c_{4} c_{5}-b_{2} c_{5}^{2}-3 c_{2} c_{5}^{2}+b_{2} b_{4} c_{6}+3 b_{4}$ $2 b_{3} c_{4} c_{5}-b_{2} c_{5}^{2}+c_{2} c_{5}^{2}+b_{2} b_{4} c_{6}-b_{4} c_{2} c_{6}+b_{2} c_{4} c_{6}-c_{2} c_{4} c_{6}, 4 c_{3}^{2} c_{4}-2$ $6 c_{2} c_{3} c_{5}+b_{2}^{2} c_{6}+6 b_{2} c_{2} c_{6}+9 c_{2}^{2} c_{6}, 4 b_{3} c_{3} c_{4}-2 b_{2} c_{3} c_{5}+2 c_{2} c_{3} c_{5}+b_{2}^{2} c_{6}$ $4 b_{3}^{2} c_{4}+8 b_{3} c_{2} c_{5}-2 b_{2} c_{3} c_{5}+2 c_{2} c_{3} c_{5}+b_{2}^{2} c_{6}-2 b_{2} c_{2} c_{6}+c_{2}^{2} c_{6}$ |

Proof. For system (43) using a computer algebra system to compute the functions $B$ and $h$ of (42). Let $\mathcal{S}$ be the set of parameters ( $a, b, c$ ) and $k_{1}, k_{2}$, and $k_{3}$ for which system (43) can be transformed to a time-reversible system (40) by a transformation (41).
$\mathcal{S}$ is the variety of the ideal $/$ with generators listed in Table intersected with $\mathrm{t} K=\left\{\left(k_{1}, k_{2}, k_{3}\right): k_{1} k_{2} k_{3} \neq 0\right\}$.
The point ( $a, b, c, k_{1}, k_{2}, k_{3}$ ) is in the set $\mathcal{S}$ if

$$
\begin{equation*}
1-k_{1} u=0,1-k_{2} v=0,1-k_{3} w=0, f=0 \quad \forall f \in I . \tag{44}
\end{equation*}
$$

Let $J=\left\langle I, 1-k_{1} u, 1-k_{2} v, 1-k_{3} w\right\rangle \subset \mathbb{C}\left[a, b, c, k_{1}, k_{2}, k_{3}, u, v, w\right]$.
Then the set of solutions of (44) is the variety of the ideal J. The Zariski closure of the projection of the variety $\mathbf{V}(J)$ onto the space of parameters $(a, b, c)$ is the variety of the six elimination ideal of $J$, the ideal $J^{(6)}$. By the Elimination Theorem to find $J^{(6)}$ one can compute a Gröbner basis of $J$ with respect to the lex order with $\left\{k_{1}, k_{2}, k_{3}, u, v, w\right\}>\{a, b, c\}$ and take from the output polynomials that depend only on $a, b$, and $c$, obtaining a basis of $J^{(6)}$. The variety $V=\mathbf{V}\left(J^{(6)}\right)$ is the Zariski closure of $\pi_{6}(\mathbf{V}(J))$. Although not all systems corresponding to points of $V$ are time-reversible, all of them admit two analytic first integrals of the form $\Psi_{1}\left(x_{1}, x_{2}, x_{3}\right)=x_{1}+\cdots$ and $\Psi_{2}\left(x_{1}, x_{2}, x_{3}\right)=x_{2} x_{3}+\cdots$, since the set of systems admitting two integrals $\Psi_{1}$ and $\Psi_{2}$ is an algebraic set.

Finally, we use the minAssGTZ command of Singular to obtain the decomposition of $J^{(6)}$ as an intersection of prime ideals, which yields the four ideals of the statement of the theorem, so that $\mathbf{V}\left(J^{(6)}\right)=\mathbf{V}\left(I_{1}\right) \cup \mathbf{V}\left(I_{2}\right) \cup \mathbf{V}\left(I_{3}\right) \cup \mathbf{V}\left(I_{4}\right)$.

$$
\begin{aligned}
& 2 a_{1}, 2 a_{5}, b_{1}-c_{1}, b_{5}-c_{5}, a_{1}\left(b_{1}+c_{1}\right), c_{4} k_{2}^{2}-b_{6} k_{3}^{2}, b_{5}^{2}+2 b_{6} b_{4}-c_{5}^{2}-2 c_{6} c_{4}, \\
& b_{2} k_{2}-3 c_{2} k_{2}+3 b_{3} k_{3}-c_{3} k_{3}, b_{5} b_{4} k_{2}^{2}-c_{5} c_{4} k_{2}^{2}+b_{6} b_{5} k_{3}^{2}-c_{6} c_{5} k_{3}^{2}, 4 a_{2} k_{2}-b_{2} k \\
& c_{3} k_{3}, 2 a_{4} k_{2}^{2}-b_{4} k_{2}^{2}-c_{4} k_{2}^{2}+2 a_{6} k_{3}^{2}+b_{6} k_{3}^{2}+c_{6} k_{3}^{2}, a_{2} b_{3}+a_{3} b_{2}+b_{3} b_{2}+2 a_{5} b_{1} \\
& -c_{3} c_{2}+2 a_{5} c_{1}-b_{5} c_{1}-c_{5} c_{1}, 2 a_{4} b_{2} k_{2}^{3}+3 b_{4} b_{2} k_{2}^{3}+b_{2} c_{4} k_{2}^{3}+2 a_{4} c_{2} k_{2}^{3}-b_{4} c_{2} k_{2}^{3} \\
& 3 b_{6} b_{3} k_{3}^{3}+b_{3} c_{6} k_{3}^{3}+2 a_{6} c_{3} k_{3}^{3}-b_{6} c_{3} k_{3}^{3}-3 c_{6} c_{3} k_{3}^{3}, 2 a_{1} b_{2} k_{2}+4 a_{2} b_{1} k_{2}+b_{2} b_{1} k_{2} \\
& +4 a_{2} c_{1} k_{2}-b_{2} c_{1} k_{2}-c_{2} c_{1} k_{2}+2 a_{1} b_{3} k_{3}+4 a_{3} b_{1} k_{3}+b_{3} b_{1} k_{3}+2 a_{1} c_{3} k_{3}+b_{1} c_{3} k_{3} \\
& 2 a_{2} b_{2} k_{2}^{2}+b_{2}^{2} k_{2}^{2}+4 a_{4} b_{1} k_{2}^{2}+2 b_{4} b_{1} k_{2}^{2}+2 b_{1} c_{4} k_{2}^{2}+2 a_{2} c_{2} k_{2}^{2}-c_{2}^{2} k_{2}^{2}+4 a_{4} c_{1} k_{2}^{2} \\
& +2 a_{3} b_{3} k_{3}^{2}+b_{3}^{2} k_{3}^{2}+4 a_{6} b_{1} k_{3}^{2}+2 b_{6} b_{1} k_{3}^{2}+2 b_{1} c_{6} k_{3}^{2}+2 a_{3} c_{3} k_{3}^{2}-c_{3}^{2} k_{3}^{2}+4 a_{6} c_{1} k_{3}^{2} \\
& 2 a_{4} b_{3} k_{2}+3 b_{4} b_{3} k_{2}+2 a_{5} k_{2}+3 b_{5} b_{2} k_{2}+b_{2} c_{5} k_{2}+b_{3} c_{4} k_{2}+2 a_{4} c_{3} k_{2}-b_{4} c_{3} k_{2} \\
& -b_{5} c_{2} k_{2}-3 c_{5} c_{2} k_{2}+2 a_{5} b_{3} k_{3}+3 b_{5} b_{3} k_{3}+2 a_{6} b_{2} k_{3}+3 b_{6} b_{2} k_{3}+b_{2} c_{6} k_{3}+b_{3} c_{5} \\
& -3 c_{5} c_{3} k_{3}+2 a_{6} c_{2} k_{3}-b_{6} c_{2} k_{3}-3 c_{6} c_{2} k_{3}
\end{aligned}
$$

Table: The Ideal I of the proof of theorem

## Example (Hu, Han, R., Physica D, 2013)

$$
\begin{align*}
& \dot{x}=x\left(a_{200} x+a_{110} y+a_{101} z\right), \\
& \dot{y}=-y+b_{200} x^{2}+b_{110} x y+b_{101} x z+b_{020} y^{2}+b_{002} z^{2},  \tag{45}\\
& \dot{z}=z+c_{200} x^{2}+c_{110} x y+c_{101} x z+c_{020} y^{2}+c_{002} z^{2} .
\end{align*}
$$

To find the necessary conditions for existence of integrals

$$
\begin{align*}
& \phi=x+\sum_{i+j+k>1} \phi_{i j k} x^{i} y^{j} z^{k}  \tag{46}\\
& \psi=y z+\sum_{i+j+k>2} \psi_{i j} x^{i} y^{j} z^{k} \tag{47}
\end{align*}
$$

using the computer algebra system Mathematica we computed polynomials $g_{\alpha}$ and $h_{\alpha}$ defined according to (26) and (27) up to $|\alpha| \leq 8$. As the result of the calculations we have obtained the ideal $\left.B_{8}=\left\langle g_{\alpha}, h_{\alpha}\right| \alpha \in \mathfrak{R},|\alpha| \leq 8\right\rangle$.

Then, we tried to find the irreducible decomposition of the variety $\mathbf{V}\left(B_{8}\right)$ of the ideal $B_{8}$ using the routine $\operatorname{minAssGTZ}$ of the computer algebra system Singular. It was not possible to complete computations on our facilities. However the linear transformation

$$
y \mapsto b y, \quad z \mapsto c z,
$$

where $b c \neq 0$, brings (45) to a quadratic system with the same linear part and $b_{011}$ is changed to $b_{011} / c$, and $c_{011}$ is changed to $c_{011} / b$. Thus, to obtain the necessary conditions for integrability of system (45) it is sufficient to consider separately the following four cases:
(i) $b_{011}=c_{011}=0($ ii $) b_{011}=0 c_{011}=1($ iii $) b_{011}=1, c_{011}=0($ iv $) b_{011}=c_{011}=1$.

## Theorem

Consider three dimensional system (45) with $b_{011}=c_{011}=0$. The system is integrable if and only if $a_{200}=0$ and one of the following conditions is satisfied:

1) $c_{200}=b_{110}+c_{101}=b_{200}=a_{101} c_{110}+b_{101} c_{020}-c_{110} c_{002}-a_{110} c_{101}$
$=a_{110} b_{101}-b_{020} b_{101}+b_{002} c_{110}+a_{101} c_{101}=0$,
2) $b_{002}^{2} c_{110}^{3}+b_{101}^{3} c_{020}^{2}=b_{020} b_{101}^{2} c_{020}-b_{002} c_{110}^{2} c_{002}=b_{020} b_{002} c_{110}+b_{101} c_{0}$ $=b_{020}^{2} b_{101}+c_{110} c_{002}^{2}=b_{020}^{3} b_{002}-c_{020} c_{002}^{3}=-b_{020}^{2} b_{002} c_{200}+b_{200} c_{020} c_{0}^{2}$
$=b_{020} b_{101} c_{200}+b_{200} c_{110} c_{002}=b_{002} c_{200} c_{110}+b_{200} b_{101} c_{020}=b_{200} b_{002} c_{11}^{2}$
$=b_{200} b_{020}-c_{200} c_{002}=-b_{020} b_{002} c_{200}^{2}+b_{200}^{2} c_{020} c_{002}=b_{101} c_{200}^{2}+b_{200}^{2} c_{1}$
$=-b_{002} c_{200}^{3}+b_{200}^{3} c_{020}=-a_{101} b_{020}+a_{110} c_{002}=a_{110} b_{101} c_{200}+a_{101} b_{200}$
$=-a_{101} b_{002} c_{110}^{2}+a_{110} b_{101}^{2} c_{020}=a_{110} b_{002} c_{110}+a_{101} b_{101} c_{020}=a_{110} b_{002} c$
$=a_{110} b_{020} b_{101}+a_{101} c_{110} c_{002}=a_{110} b_{020} b_{002} c_{200}-a_{101} b_{200} c_{020} c_{002}$
$=a_{110} b_{020}^{2} b_{002}-a_{101} c_{020} c_{002}^{2}=a_{110} b_{200}-a_{101} c_{200}=a_{110}^{2} b_{101}+a_{101}^{2} c_{110}$
$=a_{110}^{2} b_{002} c_{200}-a_{101}^{2} b_{200} c_{020}=a_{110}^{2} b_{020} b_{002}-a_{101}^{2} c_{020} c_{002}=a_{110}^{3} b_{002}-$
$=b_{110}+c_{101}=0$,
3) $c_{002}=b_{020}=b_{110}+c_{101}=a_{101}=a_{110}=0$.

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